



COTS embedded database solving dynamic points-of-interest

A Raima Inc. Technical Whitepaper

Published: September, 2008 Author: Duncan Bates

Vice President of Product Management

Copyright: Raima Inc., All rights reserved

Abstract

In navigation devices of today the This article looks at how commercial of the shelf (CTOS) database solutions can be utilized to solve the dynamic point of interest problem.

This article is relative to the following versions of RDM:

✓ RDM Embedded: All

✓ RDM Server: All



Contents

Abstract	1
Introduction	
Commercial off the Shelf (COTS) Solution	
Implementation	
Conclusion	
Complete Source	
References	
Contact Information	_
Contact Information	q



Introduction

Navigation systems found in cars and handheld units provide an efficient and easy way to lookup points of interest in a city, find the best route to a user's destination and provide other regionally-based operations by efficiently managing map points. A typical query for these devices is for example locating the nearest Italian restaurant based on the current position of the vehicle. Proprietary data sets and indexing algorithms are used to solve these types of queries, but a major drawback with most of these devices is that they are 'read only' to prevent users from making changes and corrupting the dataset. Updates to datasets must be done in batch mode, and the complete dataset and indexes must be rebuilt on a regular basis because new businesses are constantly cropping up and new roads and buildings are being constructed. Vendors are therefore unable to offer customers localized datasets which could be sold at gas stations and other venues, nor can users make route calculations on the fly to avoid ad-hoc obstacles like accidents.

Commercial off the Shelf (COTS) Solution

COTS embedded databases are designed to manage changing datasets and indexes without the chance of data corruption, but they have a different problem - they don't support two dimensional indexes needed to efficiently manage points-of-interest. If we can find a solution where COTS engines could be used, navigation vendors would be able to design more robust devices and provide new services to their customers.

The problem stems from the fact that a point of interest must be indexed based on both its longitude and latitude value where neither of the two values is favored. By default a one dimensional index will favor one of the two values making a range query very inefficient, which is the main reason why vendors create their own proprietary solutions.

. 2								Long	jitude V	alues							
		0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
	0	(0,0)	(1,0)	(2,0)	(3,0)	(4,0)	(5,0)	(6,0)	(7,0)	(8,0)	(9,0)	(10,0)	(11,0)	(12,0)	(13,0)	(14,0)	(15,0)
	1	(0,1)	(1,1)	(2,1)	(3,1)	(4,1)	(5,1)	(6,1)	(7,1)	(8,1)	(9,1)	(10,1)	(11,1)	(12,1)	(13,1)	(14,1)	(15,1)
1	2	(0,2)	(1,2)	(2,2)	(3,2)	(4,2)	(5,2)	(6,2)	(7,2)	(8,2)	(9,2)	(10,2)	(11,2)	(12,2)	(13,2)	(14,2)	(15,2)
	3	(0,3)	(1,3)	(2,3)	(3,3)	(4,3)	(5,3)	(6,3)	(7,3)	(8,3)	(9,3)	(10,3)	(11,3)	(12,3)	(13,3)	(14,3)	(15,3)
	4	(0,4)	(1,4)	(2,4)	(3,4)	(4,4)	(5,4)	(6,4)	(7,4)	(8,4)	(9,4)	(10,4)	(11,4)	(12,4)	(13,4)	(14,4)	(15,4)
	5	(0,5)	(1,5)	(2,5)	(3,5)	(4,5)	(5,5)	(6,5)	(7,5)	(8,5)	(9,5)	(10,5)	(11,5)	(12,5)	(13,5)	(14,5)	(15,5)
S A C	6	(0,6)	(1,6)	(2,6)	(3,6)	(4,6)	(5,6)	(6,6)	(7,6)	(8,6)	(9,6)	(10,6)	(11,6)	(12,6)	(13,6)	(14,6)	(15,6)
	7	(0,7)	(1,7)	(2,7)	(3,7)	(4,7)	(5,7)	(8,7)	(7,7)	(8,7)	(9,7)	(10,7)	(11,7)	(12,7)	(13,7)	(14,7)	(15,7)
Larrude	8	(0,8)	(1,8)	(2,8)	(3,8)	(4,8)	(5,8)	(6,8)	(7,8)	(8,8)	(9,8)	(10,8)	(11,8)	(12,8)	(13,8)	(14,8)	(15,8)
3	9	(0,9)	(1,9)	(2,9)	(3,9)	(4,9)	(5,9)	(6,9)	(7,9)	(8,9)	(9,9)	(10,9)	(11,9)	(12,9)	(13,9)	(14,9)	(15,9)
	10	(0,10)	(1,10)	(2,10)	(3,10)	(4,10)	(5,10)	(6,10)	(7,10)	(8,10)	(9,10)	(10,10)	(11,10)	(12,10)	(13,10)	(14,10)	(15,10)
1	11	(0,11)	(1,11)	(2,11)	(3,11)	(4,11)	(5,11)	(6,11)	(7.11)	(8,11)	(9,11)	(10,11)	(11,11)	(12,11)	(13,11)	(14,11)	(15,11)
	12	(0,12)	(1,12)	(2,12)	(3,12)	(4,12)	(5,12)	(6,12)	(7,12)	(8,12)	(9,12)	(10,12)	(11,12)	(12,12)	(13,12)	(14,12)	(15,12)
	13	(0,13)	(1,13)	(2,13)	(3,13)	(4,13)	(5,13)	(6,13)	(7,13)	(8,13)	(9,13)	(10,13)	(11,13)	(12,13)	(13,13)	(14,13)	(15,13)
	14	(0,14)	(1,14)	(2,14)	(3,14)	(4,14)	(5,14)	(6,14)	(7.14)	(8,14)	(9,14)	(10,14)	(11,14)	(12,14)	(13,14)	(14,14)	(15,14)
	15	(0,15)	(1,15)	(2,15)	(3,15)	(4,15)	(5,15)	(6,15)	(7,15)	(8,15)	(9,15)	(10,15)	(11,15)	(12,15)	(13,15)	(14,15)	(15,15)

Figure 1



Figure 1 is a longitude, latitude grid of all points in a system where both the longitude and latitude are coded as 4 bit values. In real world applications these values would be 32 bit but for the simplicity of describing both the problem and solution, the maps in this article will be based on 4 bit data types.

A one dimensional index, such as a B-Tree, will only provide an efficient longitude/latitude index in one direction. In the figure, the longitude values are illustrated as the most significant information so the index will only have vertical efficiency. Think of the value in each cell as what the index sees, and the index is sorted from low to high.

If we add a region query based on the bounding box between (5, 5) to (9, 8) this would translate to a range scan of the index between the two values. Figure 2 illustrates exactly that.

12								Long	jitude V	alues							
		0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
	0	(0,0)	(1,0)	(2,0)	(3,0)	(4,0)	(5,0)	(6,0)	(7,0)	(8,0)	(9,0)	(10,0)	(11,0)	(12,0)	(13,0)	(14,0)	(15,0)
	1	(0,1)	(1,1)	(2,1)	(3,1)	(4,1)	(5,1)	(6,1)	(7,1)	(8,1)	(9,1)	(10,1)	(11,1)	(12,1)	(13,1)	(14,1)	(15,1)
3	2	(0,2)	(1,2)	(2,2)	(3,2)	(4,2)	(5,2)	(6,2)	(7,2)	(8,2)	(9,2)	(10,2)	(11,2)	(12,2)	(13,2)	(14,2)	(15,2)
	3	(0,3)	(1,3)	(2,3)	(3,3)	(4,3)	(5,3)	(6,3)	(7,3)	(8,3)	(9,3)	(10,3)	(11,3)	(12,3)	(13,3)	(14,3)	(15,3)
	4	(0,4)	(1,4)	(2,4)	(3,4)	(4,4)	(5,4)	(6,4)	(7.4)	(8,4)	(9,4)	(10,4)	(11,4)	(12,4)	(13,4)	(14,4)	(15,4)
	5	(0,5)	(1,5)	(2,5)	(3,5)	(4,5)	(5,5)	(6,5)	(7,5)	(8,5)	(9,5)	(10,5)	(11,5)	(12,5)	(13,5)	(14,5)	(15,5)
	6	(0,6)	(1,6)	(2,6)	(3,6)	(4,6)	(5,6)	(8,8)	(7,6)	(8,6)	(9,6)	(10,6)	(11,6)	(12,6)	(13,6)	(14,6)	(15,6)
	7	(0,7)	(1,7)	(2,7)	(3,7)	(4,7)	(5,7)	(8,7)	(7,7)	(8,7)	(9,7)	(10,7)	(11,7)	(12,7)	(13,7)	(14,7)	(15,7)
	8	(0,8)	(1,8)	(2,8)	(3,8)	(4,8)	(5,8)	(6,8)	(7,8)	(8,8)	(9,8)	(10,8)	(11,8)	(12,8)	(13,8)	(14,8)	(15,8)
	9	(0,9)	(1,9)	(2,9)	(3,9)	(4,9)	(5,9)	(6,9)	(7,9)	(8,9)	(9,9)	(10,9)	(11,9)	(12,9)	(13,9)	(14,9)	(15,9)
. 3	10	(0,10)	(1,10)	(2,10)	(3,10)	(4,10)	(5,10)	(6,10)	(7,10)	(8,10)	(9,10)	(10,10)	(11,10)	(12,10)	(13,10)	(14,10)	(15,10)
	11	(0,11)	(1,11)	(2,11)	(3,11)	(4,11)	(5,11)	(8,11)	(7,11)	(8,11)	(9,11)	(10,11)	(11,11)	(12,11)	(13,11)	(14,11)	(15,11)
	12	(0,12)	(1,12)	(2,12)	(3,12)	(4,12)	(5,12)	(6,12)	(7,12)	(8,12)	(9,12)	(10,12)	(11,12)	(12,12)	(13,12)	(14,12)	(15,12)
	13	(0,13)	(1,13)	(2,13)	(3,13)	(4,13)	(5,13)	(6,13)	(7,13)	(8,13)	(9,13)	(10,13)	(11,13)	(12,13)	(13,13)	(14,13)	(15,13)
	14	(0,14)	(1,14)	(2,14)	(3,14)	(4,14)	(5,14)	(6,14)	(7.14)	(8,14)	(9,14)	(10,14)	(11,14)	(12,14)	(13,14)	(14,14)	(15,14)
1	15	(0,15)	(1,15)	(2,15)	(3,15)	(4,15)	(5,15)	(6,15)	(7,15)	(8,15)	(9,15)	(10,15)	(11,15)	(12,15)	(13,15)	(14,15)	(15,15)

Figure 2

Not only are the yellow points returned to the application but also all the false gray points that are clearly outside the bounding box. This inefficiency is the major reason for navigational vendors implementing proprietary solutions based on two dimensional indexing algorithms like R-Tree or any of its cousins. By making the proprietary implementation read only, the vendors don't need to implement transactional safety or concurrency control to avoid corruption or allow multi-threaded application access to the data.



Implementation

This article will describe a solution to the two dimensional problem by mapping it down to one dimension allowing us to leverage all the investments done in the embedded database space. This not only allows the vendors to efficiently query these points-of- interest but also allows them to dynamically add other one dimensional information to the query, like type (gas station, restaurant, etc), which can't be solved with a two dimensional index system.

If you look at the previous figure, the one dimensional index is inefficient since its most significant piece of information is taken from the Longitude values and the second most significant from the latitude, thus creating the undesired vertical efficiency. If you translate the points into the bit pattern used by the indexing system it will look like this:

_								ما	ngitude V	alues							
L		0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
	0	00000000	00010000	00100000	00110000	01000000	01010000	01100000	01110000	10000000	10010000	10 100000	10110000	11000000	11010000	11100000	11110000
I	1	00000001	00010001	00100001	00110001	01000001	01010001	01100001	01110001	10000001	10010001	10 100001	10110001	11000001	11010001	11100001	11110001
	2	00000010	00010010	00100010	00110010	01000010	01010010	01100010	01110010	10000010	10010010	10 1000 10	10110010	11000010	11010010	11100010	11110010
L	3	00000011	00010011	00100011	00110011	01000011	01010011	01100011	01110011	10000011	10010011	10 100011	10110011	11000011	11010011	11100011	11110011
	4	00000100	00010100	00100100	00110100	01000100	01010100	01100100	01110100	10000100	10010100	10 100 100	10110100	11000100	11010100	11100100	11110100
	5	00000101	00010101	00100101	00110101	01000101	01010101	01100101	01110101	10000101	10010101	10 100 101	10110101	11000101	11010101	11100101	11110101
s L	6	00000110	00010110	00100110	00110110	01000110	01010110	01100110	01110110	10000110	10010110	10 100 110	10110110	11000110	11010110	11100110	11110110
<u> </u>	7	00000111	00010111	00100111	00110111	01000111	01010111	01100111	01110111	10000111	10010111	10 100 111	10110111	11000111	11010111	11100111	11110111
atritude	8	00001000	00011000	00101000	00111000	01001000	01011000	01101000	01111000	10001000	10011000	10 10 1000	10111000	11001000	11011000	11101000	111111000
<u> </u>	9	00001001	00011001	00101001	00111001	01001001	01011001	01101001	01111001	10001001	10011001	10 10 100 1	10111001	11001001	11011001	11101001	111111001
L	10	00001010	00011010	00101010	00111010	01001010	01011010	01101010	01111010	10001010	10011010	10 10 10 10	10111010	11001010	11011010	11101010	111111010
L	11	00001011	00011011	00101011	00111011	01001011	01011011	01101011	01111011	10001011	10011011	10101011	10111011	11001011	11011011	11101011	111111011
	12	00001100	00011100	00101100	00111100	01001100	01011100	01101100	011111100	10001100	10011100	10 101 100	101111100	11001100	11011100	11101100	111111100
	13	00001101	00011101	00101101	00111101	01001101	01011101	01101101	011111101	10001101	10011101	10101101	101111101	11001101	11011101	11101101	111111101
	14	00001110	00011110	00101110	00111110	01001110	01011110	01101110	011111110	10001110	10011110	10 101110	101111110	11001110	11011110	11101110	111111110
	15	00001111	00011111	00101111	00111111	01001111	01011111	01101111	01111111	10001111	10011111	10101111	10111111	11001111	11011111	11101111	111111111

Figure 3

The four most significant bits $(x_4x_3x_2x_4)$ stem from the Longitude value and the 4 second most significant bits $(y_4y_3y_2y_4)$ stem from the Latitude. Let's introduce the Z-value¹, which is made up of interleaving the most significant bits from both dimensions, resulting in values on the form $(y_4x_4y_3x_3y_2x_2y_1x_1)$. If our one dimensional index uses this bit pattern as its index values we'll be indexing something where the most significant information from both dimensions is taken into consideration. Figure 4 shows the pattern.

¹ Morton, G. M. (1966), A computer Oriented Geodetic Data Base; and a New Technique in File Sequencing, Technical Report, Ottawa, Canada: IBM Ltd.



	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	00000000	00000001	00000 100	e reew	00010000	00010001	000 10 100 20		01000000	- 20	01000100 68	- 100	01010000	01010001	OL 500000	
1	00000010	00000011 3	00000 110 6	00000111 7	00010010 18	00010011 19	000 10110 22	00010111 23	01000010 66	01000011 67	01000110 70	01000111 71	01010010 82	01010011 83	01010110 86	010101 87
2	00001000	00001001	00001100	00001101	00011000	00011001	000 11100	00011101	01001000	01001001	01001100	01001101	01011000	01011001	01011100	010111
	8	9	12	13	24	25	28	29	72	73	76	77	88	89	92	93
3	00001010	00001011	00001110	00001111	00011010	00011011	000 11110	00011111	01001010	01001011	01001110	01001111	01011010	0101 1011	01011110	010111
	10	11	14	15	26	27	30	31	74	75	78	79	90	91	94	95
4	00100000	00100001	00100100	00100101	00110000	00110001	001 10100	00110101	01100000	01100001	01 100 100	01100101	01110000	01110001	01110100	011101
	32	33	36	37	48	49	52	53	96	97	100	101	112	113	116	117
5	00100010	00100011	00100110	00100111	00110010	00110011	001 10110	00110111	01100010	01100011	01 100110	01100111	01110010	01110011	01110110	011101
	34	35	38	39	50	51	54	55	98	99	102	103	114	115	118	119
6	00101000	00101001	00101100	00101101	00111000	00111001	00111100	00111101	01101000	01101001	01 101 100	01101101	01111000	01111001	01111100	011111
	40	41	44	45	56	57	60	61	104	105	108	109	120	121	124	125
7	00101010	00101011	00101110	00101111	00111010	00111011	00111110	00111111	01101010	01101011	01 101110	01101111	01111010	01111011	01111110	01111
	42	43	46	47	58	59	62	63	106	107	110	111	122	123	126	127
8	10000000	10000001	10000 100	10000101	10010000	10010001	100 10 100	10010101	11000000	11000001	11000100	11000101	11010000	11010001	11010100	11010
	128	129	132	133	144	145	148	149	192	193	196	197	208	209	212	213
9	10000010	10000011	10000 110	10000111	10010010	10010011	100 101 10	10010111	11000010	110000 11	11000110	11000111	11010010	11010011	11010110	11010
	130	131	134	135	146	147	150	151	194	195	198	199	210	211	214	215
10	10001000	10001001	10001 100	10001101	10011000	10011001	100 11100	10011101	11001000	11001001	11001100	11001101	11011000	1101 1001	11011100	11011
	136	137	140	141	152	153	156	157	200	201	204	205	216	217	220	221
11	10001010	10001011	10001110	10001111	10011010	10011011	100 11110	10011111	11001010	11001011	11001110	11001111	11011010	11011011	11011110	11011
	138	139	142	143	154	155	158	159	202	203	206	207	218	219	222	223
12	10100000	10100001	10100100	10100101	10110000	10110001	101 10100	10110101	11100000	11100001	11 100 100	11100101	11110000	11110001	11110100	11110
	160	161	164	165	176	177	180	181	224	225	228	229	240	241	244	24
13	10100010	10100011	10100110	10100111	10110010	10110011	101 101 10	10110111	11100010	111000 11	11 100 110	11100111	11110010	11110011	11110110	11110
	162	163	166	167	178	179	182	183	226	227	230	231	242	243	246	247
14	10101000	10101001	10101 100	10101101	10111000	10111001	101 11100	10111101	11101000	11101001	11 101100	11101101	11111000	11111001	111111100	11111
	168	169	172	173	184	185	188	189	232	233	236	237	248	249	252	25:
15	10101010	10101011 171	10101110 174	10101111 175	10111010 186	10111011 187	101 11110 190	10111111	11101010 234	11101011 235	11 101110 238	11101111 239	11111010 250	11111011 251	111111110 254	11111 25:

Figure 4

For illustration purposes each cell has both the binary and decimal representation of the Z-Values. Instead of having vertical efficiency we've now managed to introduce square like efficiency, but we still can't take any random region and expect an efficient result. If our bounding box happened to be from (0, 0) to (3, 3) or (6, 6) to (7, 7) we'd be extremely efficient since any query will be mapped to a range query and all points in our region have contiguous increasing value. E.g. the (0, 0) to (3, 3) bounding box resulting in a range query from 0 to 15.

Let's look at the range query from (5, 5) to (9, 8) that we were initially working on, How would that look?



	9						ما	ngitude V	alues							
	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	00000000	00000001	00000 100	00000101	00010000	00010001	000 10100	00010101	01000000	01000001	01000100	01000101	01010000	01010001	01010100	01010101
	0	1	4	5	16	17	20	21	64	65	68	69	80	81	84	85
1	00000010	00000011	00000 110	00000111	00010010	00010011	000 10110	00010111	01000010	01000011	01000110	01000111	01010010	01010011	01010110	0101011
	2	3	6	7	18	19	22	23	66	67	70	71	82	83	86	87
2	00001000	00001001	00001 100	00001101	00011000	00011001	000 11100	00011101	01001000	01001001	01001100	01001101	01011000	0101 1001	01011100	0101110
	8	9	12	13	24	25	28	29	72	73	76	77	88	89	92	93
3	00001010	00001011	00001110	00001111	00011010	00011011	000 11110	00011111	01001010	01001011	01001110	01001111	01011010	0101 1011	01011110	0101111
	10	11	14	15	26	27	30	31	74	75	78	79	90	91	94	95
4	00100000	00100001	00100100	00100101	00110000	00110001	001 10100	00110101	01100000	01100001	01 100 100	01100101	01110000	01110001	01110100	0111010
	32	33	36	37	48	49	52	53	96	97	100	101	112	113	116	117
5	00100010	00100011	00100110	00100111	00110010	00110011	001 10110	00110111	01100010	01100011	01 100110	01100111	01110010	01110011	01110110	0111011
	34	35	38	39	50	51	54	55	98	99	102	103	114	115	118	119
6	00101000	00101001	00101100	00101101	00111000	00111001	00111100	00111101	01101000	01101001	01 101 100	01101101	01111000	01111001	01111100	0111110
	40	41	44	45	56	57	60	61	104	105	108	109	120	121	124	125
7	00101010	00101011	00101110	00101111	00111010	00111011	00111110	00111111	01101010	01101011	01 101110	01101111	01111010	01111011	01111110	0111111
	42	43	46	47	58	59	62	63	106	107	110	111	122	123	126	127
8	10000000	10000001	10000 100	10000101	10010000	10010001	100 10 100	10010101	11000000	11000001	11000100	11000101	11010000	11010001	11010100	1101010
	128	129	132	133	144	145	148	149	192	193	196	197	208	209	212	213
9	10000010	10000011	10000 110	10000111	10010010	10010011	100 101 10	10010111	11000010	110000 11	11000110	11000111	11010010	11010011	11010110	1101011
	130	131	134	135	146	147	150	151	194	195	198	199	210	211	214	215
10	10001000	10001001	10001 100	10001101	10011000	10011001	100 11 100	10011101	11001000	11001001	11001100	11001101	11011000	1101 1001	11011100	1101110
	136	137	140	141	152	153	156	157	200	201	204	205	216	217	220	221
11	10001010	10001011	10001110	10001111	10011010	10011011	100 11110	10011111	11001010	11001011	11001110	11001111	11011010	1101 1011	11011110	1101111
	138	139	142	143	154	155	158	159	202	203	206	207	218	219	222	223
12	10100000	10100001	10100100	10100101	10110000	10110001	101 10100	10110101	11100000	11100001	11 100 100	11100101	11110000	11110001	11110100	1111010
	160	161	164	165	176	177	180	181	224	225	228	229	240	241	244	245
13	10100010	10100011	10100110	10100111	10110010	10110011	101 101 10	10110111	11100010	111000 11	11 100110	11100111	11110010	11110011	11110110	1111011
	162	163	166	167	178	179	182	183	226	227	230	231	242	243	246	247
14	10101000	10101001	10101100	10101101	10111000	10111001	101 11100	10111101	11101000	11101001	11 101 100	11101101	11111000	11111001	111111100	1111110
	168	169	172	173	184	185	188	189	232	233	236	237	248	249	252	253
15	10101010	10101011	10101110	10101111	10111010	10111011	101 11110	10111111	11101010	11101011	11 101110	11101111	11111010	11111011	111111110	11111111
	170	171	174	175	186	187	190	191	234	235	238	239	250	251	254	255

Figure 5

A straight forward range query of this region would return a whole lot of false points, (the grey points), which make this just as inefficient as the previous discussion. So the question is, can we optimize our query? The answer is yes. Since our points are now organized in squares we can take the region and break it down into multiple squares of contiguous increasing index values. You'll see from the rest of this discussion that the proposed algorithm for calculating these squares will result in our yellow region being broken into 5 smaller squares, scanned separately, optimizing out most of the false points.

00110011	00110110	00110111	01100010	01100011
51	54	55	98	99
00111001	00111100	00111101	01101000	01101001
57	60	61	104	105
00111011	00111110	00111111	01101010	01101011
59	62	63	106	107
10010001	10010100	10010101	11000000	11000001
145	148	149	192	193

We'll start out by doing a range query from 51 to 193, which are our bounding box values. As we scan we'll decide to calculate a region division if 3 false points are reported. We allow up to 3 false points to avoid too many division calculations. In our case the first division calculation will take place when the last reported point is above 63 and lower than 98 given that there are more than 3 points to report in this interval.



To illustrate the division calculation we've broken out the bounding box values in binary form:

```
51 = 00110011 = (0101,0101), and 193 = 11000001 = (1001,1000)
```

The first thing we do is look at the Z value and determine the first significant bit that differs based on the values; this will determine whether we're looking at a vertical or a horizontal division. With the above numbers the identified bit is z_8 which translates to the y_4 bit. Y bits will result in a horizontal split, x bits vertical.

Since we've identified a vertical split we know that the upper x boundary can be inherited from the 193 value and the lower x boundary from the 51. The two points we want to identify in this division (we'll call them LitMax and BigMin) are 107 and 145 which are the highest number in the upper square and lowest number in the bottom square divided by the red line. What we don't know is the y value just above and below this division line. LitMax's y value can be calculated as 'all common most significant bits' from the bounding box y values followed by a 0 and then 1's, and the BigMin's y value would be 'all common most significant bits' followed by 1 and then 0's.

So in our case we take the y's from 51 and 193 and look at the bit patterns:

```
51's y = 0101
193'2 y = 1000
```

This gives us the LitMax y value to be 0111 (no common bits), and BigMin's y value 1000 resulting in the LitMax point being (1001,0111) and BigMin's point being (0101,1000) interleaved resulting in 01101011 = 107 and 10010001 = 145.

Now that the calculation is done, our initial bounding box (5,5) to (9,8) is split in two - (5,5) to (9,7) and (5,8) to (9,8) . Since our last reported point was between 63 and 98 (less than LitMax) there is a chance of finding more valid points in the first region so we do a recursive call into the division algorithm with the new bounding box values, 51 to 107.

```
51 = 00110011 = (0101,0101), and 107 = 01101011 = (1001,0111)
```

Identifying that x_4 is the first significant bit that changes, means a vertical split where we inherit the y values from the bounding box extent. The LitMax and BigMin values are now computed based on the x values in the same way as our first calculation, resulting in the LitMax point being (0111,0111) and BigMin point being (1000,0101) interleaved 00111111 = 63 and 01100010 = 98 dividing along the blue line. We still know that the last valid point was between 63 and 98, so we can start a regular scan from 98 and 107 which is our new bounding box. The new scan will result in new splits but at one point we'll return to the last reported value being larger than 107 and we'll start a regular scan from the BigMin calculated in our first split.

With our original bounding box we'll end up with 4 splits and 4 scans with a maximum of (4-1) * 3 false points reported.

There are another couple of observations to make: first the z value is a loss less representation of the x and y, so by storing z there is no need to store the x and y value. Another observation is that z is now just indexed as a one dimensional value; pre-pending it with any other one dimensional value would allow for even more specialized queries. Say you pre-pend it with type information than you can efficiently index any gas stations, any restaurants or any other type that you may discover at runtime without needing to ship the software with a predefined set of types.



Conclusion

To conclude the above discussion allows commercial off the shelf databases to dynamically and efficiently manage points-of-interest data without the need for specialized indexing techniques. It also supports on-device changes of data without the possibility of corruption.

Complete Source

Please download Raima's RDM Embedded technology for a running example of the problem described in this article, http://www.raima.com/products/rdm-embedded/sdk-download/

References

Z-order (curve). (2008, July 26). In *Wikipedia, The Free Encyclopedia*. Retrieved 19:44, September 10, 2008, from http://en.wikipedia.org/w/index.php?title=Z-order (curve)&oldid=228028274

Morton, G. M. (1966), A computer Oriented Geodetic Data Base; and a New Technique in File Sequencing, Technical Report, Ottawa, Canada: IBM Ltd.

Tropf, H. & Herzog, H. (1981), "Multidimensional Range Search in Dynamically Balanced Trees", *Angewandte Informatik* 2: 71–77.

Contact Information

Website: http://www.raima.com

WORLDWIDE

Raima Inc.

720 Third Avenue, Suite 1100

Seattle, WA 98104

Telephone: +1 206 748 5300

Fax: +1 206 748 5200 E-mail: <u>sales@raima.com</u>

EUROPE

Raima Inc.

Stubbings House, Henley Road

Maidenhead SL6 6QL United Kingdom

Telephone: +44 1628 826 800 Fax: +44 1628 825 343

E-mail: sales@raima.com